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Quality Assessment of Resultant Images after Processing

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Abstract

Image quality is a characteristic of an image that measures the perceived image degradation, typically, compared to an ideal or perfect image. Imaging systems may introduce some amounts of distortion or artifacts in the signal, so the quality assessment is an important problem. Processing of images involves complicated steps. The aim of any processing result is to get a processed image which is very much same as the original. It includes image restoration, enhancement, compression and many more. To find if the reconstructed image after compression has lost the originality is found by assessing the quality of the image. Traditional perceptual image quality assessment approaches are based on measuring the errors (signal differences between the distorted and the reference images and attempt to quantify the errors in a way that simulates human visual error sensitivity features. A discussion is proposed here in order to assess the quality of the compressed image and the relevant information of the processed image is found.

Keywords: Reference methods, Quality Assessment, Lateral chromatic aberration, Root Mean Squared Error, Peak Signal to Noise Ratio, Signal to Noise Ratio, Human Visual System.

1. Introduction

Interest in image processing methods stem from two principal application areas, improvement of pictorial information for human interpretation and processing of scene data for autonomous machine perception. One of the first applications of image processing techniques in the first category was in improving digitized newspaper pictures sent by submarine cable between London and New York. An image may be defined as a monochrome image or simply image, two-dimensional function, $f(x, y)$ where x and y are spatial coordinates and (x, y) is called the intensity of f are all finite, discrete quantities, the image is called a digital image. A digital image is an image $f(x, y)$ that has been discretized both in spatial coordinates and brightness. A digital image can be considered a matrix whose row and column indices identify a point in the image and the corresponding matrix element value identifies the gray level at that point. The elements of such a digital array are called image elements, picture elements, pixels or pels.

Digital image processing encompassed a broad range of hardware, software, and theoretical underpinnings. There are basic fundamental steps required to perform an image processing task. The overall objective is to produce a result from a problem domain by means of image processing. A piece of mail is taken as an example objective is to read the address on each piece. Thus the desired output in this case is a stream of alphanumeric characters. The first step in the image processing process is the image acquisition –that is, to acquire a digital image. Acquiring the image requires an imaging sensor and the capability to digitize the signal produced by the sensor. The imaging sensor could be a monochrome or color TV camera that produces a two-dimensional image at a time. After the digital image has been obtained, the next step deals with preprocessing that image. The key function of preprocessing is to improve the image in ways that increase the chances for success of the other processes, like enhancing the contrast, removing

noise and isolating regions whose texture indicate a likelihood of alphanumeric information or may be images with graphics.

The next stage deals with segmentation. Segmentation partitions an input image into its constituent parts or objects. In general, autonomous segmentation is one of the most difficult tasks in digital image processing. On the other hand, a rugged segmentation procedure brings the process a long way toward successful solution of an imaging problem. The output of segmentation stage usually is raw pixel data, constituting either the boundary of a region or all the points in the region itself. In either case, converting the data to a form suitable for computer processing is necessary. The first decision that must be made is whether the data should be represented as a boundary or as a complete region. Boundary representation is appropriate when the focus is on internal properties, such as corners and inflections. Regional representation is appropriate when the focus is on internal properties, such as texture or skeletal shape. Choosing a representation is only a part of the solution for transforming raw data into a form suitable for subsequent computer processing. A method must also be specified for describing the data so that features of interest are highlighted. Description also called feature selection, deals with extracting features that result in some quantitative information of interest.

The last stage involves recognition and interpretation. Recognition is the process that assigns a label to an object based on the information provided by its descriptors. Interpretation involves assigning meaning to an ensemble of recognized objects. Finally the result is obtained. If the problem domain requires image compression then this addresses the problem of reducing the amount of data required to represent a digital image. It is a process intended to yield a compact representation of an image, thereby reducing the image storage/transmission requirements.

2. Assessment of quality of image

Traditional perceptual image quality assessment approaches are based on measuring the errors (signal differences) between the distorted and the reference images, and attempt to quantify the errors in a way that simulates human visual error sensitivity features [1]. These methods usually involve 1. A channel decomposition process that transforms the image signals into different spatial frequency as well as orientation selective subbands. 2. An error normalization process that weights the error signal in each subband by incorporating the variation of visual sensitivity in different subbands (often related to a contrast sensitivity function), and the variation of visual error sensitivity caused by intra- or inter-channel neighboring transform coefficients (often related to certain visual masking effects) . 3. An error pooling process that combines the error signals in different subbands into a single quality/distortion value.

An image source communicates to a receiver through a channel that limits the amount of information that could flow through it, thereby introducing distortions [2]. The output of the image source is the reference image, the output of the channel is the test image, and the goal is to relate the visual quality of the test image to the amount of information shared between the test and the reference signals, or more precisely, the mutual information between them [3]. Although mutual information is a statistical measure of information fidelity, and may only be loosely related with what humans regard as image information, it places fundamental limits on the amount of cognitive information that could be extracted from an image. For example, in cases where the channel is distorting images severely, corresponding to low mutual information between the test and the reference, the ability of human viewers to obtain semantic information by discriminating and identifying objects in images is also hampered. Thus, information fidelity methods exploit the relationship between statistical image information and visual quality. While these approaches can conveniently make use of many known psychophysical features of the human visual systems, they are based on some strong assumptions, which are difficult to validate [4].

3 Information Theoretic Approaches to Image Quality Assessment

Explored information-theoretic approaches to the quality assessment problem, where the quality assessment problem is viewed as an information-fidelity problem rather than a signal-fidelity problem has been explored.. An image source communicates to a receiver through a channel that limits the amount of information that could flow through it, thereby introducing distortions. The output of the image source is the reference image, the output of the channel is

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4. Structural Similarity Based Image and Video Quality Assessment

Different from traditional error-sensitivity based approach, structural similarity based image quality assessment is based on the following philosophy: The main function of the human visual system is to extract structural information from the viewing field, and the human visual system is highly adapted for this purpose. Therefore, a measurement of structural information loss can provide a good approximation to perceived image distortion. Here, we regard the structural information in an image as those attributes that reflect the structure of objects in the scene, independent of the average luminance and contrast. A universal image quality index that separates the comparison of luminance, contrast and structure was introduced. This approach was generalized and improved, leading to a Structural SIMilarity Index (SSIM), which had shown clear advantages over traditional mean squared error (MSE) and peak signal to noise ratio (PSNR) measures when tested on a database of JPEG and JPEG2000 compressed images. This SSIM index has also been applied for video quality assessment and extended to a multi-scale approach [8],[9],[10].

In digital or film-based photography, an image is formed on the image plane of the camera and then measured electronically or chemically to produce the photograph. The image formation process may be described by the ideal pinhole camera model, where only light rays from the depicted scene that pass through the camera aperture can fall on the image plane. In reality, this ideal model is only an approximation of the image formation process, and image quality may be described in terms of how well the camera approximates the pinhole model.

An ideal model of how a camera measures light is that the resulting photograph should represent the amount of light that falls on each point at a certain point in time. This model is only an approximate description of the light measurement process of a camera, and image quality is also related to the deviation from this model.

In some cases, the image for which quality should be determined is primarily not the result of a photographic process in a camera, but the result of storing or transmitting the image. A typical example is a digital image that has been compressed, stored or transmitted, and then decompressed again. Unless a lossless compression method has been used, the resulting image is normally not identical to the original image and the deviation from the (ideal) original image is then a measure of quality. By considering a large set of images, and determining a quality measure for each of them, statistical methods can be used to determine an overall quality measure of the compression method.

In a typical digital camera, the resulting image quality depends on all three factors mentioned above: how much the image formation process of the camera deviates from the pinhole model, the quality of the image measurement process, and the coding artifacts that are introduced in the image produced by the camera, typically by the JPEG coding method.

By defining image quality in terms of a deviation from the ideal situation, quality measures become technical in the sense that they can be objectively determined in terms of deviations from the ideal models. Image quality can, however, also be related to the subjective perception of an image, e.g., a human looking at a photograph. Examples are how colors are represented in a black-and-white image, as well as in color images, or that the reduction of image quality from noise depends on how the noise correlates with the information the viewer seeks in the image rather than its overall strength. Another example of this type of quality measure is Johnson's criteria for determining the necessary quality of an image in order to detect targets in night vision systems.

Subjective measures of quality also relate to the fact that, although the camera's deviation from the ideal models of

image formation and measurement in general is undesirable and corresponds to reduced objective image quality, these deviations can also be used for artistic effects in image production, corresponding to high subjective quality.

4.1 Image quality assessment categories

There are several techniques and metrics that can be measured objectively and automatically evaluated by a computer program. Therefore, they can be classified as full-reference (FR) methods and no-reference (NR) methods. In FR image quality assessment methods, the quality of a test image is evaluated by comparing it with a reference image that is assumed to have perfect quality. NR metrics try to assess the quality of an image without any reference to the original one. For example, comparing an original image to the output of JPEG compression of that image is full-reference – it uses the original as reference.

5. Image quality factors

5.1 Sharpness determines the amount of detail an image can convey. System sharpness is affected by the lens (design and manufacturing quality, focal length, aperture, and distance from the image center) and sensor (pixel count and anti-aliasing filter). In the field, sharpness is affected by camera shake (a good tripod can be helpful), focus accuracy, and atmospheric disturbances (thermal effects and aerosols). Lost sharpness can be restored by sharpening, but sharpening has limits. Oversharpening, can degrade image quality by causing "halos" to appear near contrast boundaries. Images from many compact digital cameras are oversharpened.

5.2 Noise is a random variation of image density, visible as grain in film and pixel level variations in digital images. It arises from the effects of basic physics— the photon nature of light and the thermal energy of heat— inside image sensors. Typical noise reduction (NR) software reduces the visibility of noise by smoothing the image, excluding areas near contrast boundaries. This technique works well, but it can obscure fine, low contrast detail.

5.3 Dynamic range (or exposure range) is the range of light levels a camera can capture, usually measured in f-stops, Exposure Value (EV), or zones (all factors of two in exposure). It is closely related to noise: high noise implies low dynamic range.

5.4 Tone reproduction is the relationship between scene luminance and the reproduced image brightness.

5.5 Contrast, also known as gamma, is the slope of the tone reproduction curve in a log-log space. High contrast usually involves loss of dynamic range — loss of detail, or clipping, in highlights or shadows.

5.6 Color accuracy is an important but ambiguous image quality factor. Many viewers prefer enhanced color saturation; the most accurate color isn't necessarily the most pleasing. Nevertheless it is important to measure a camera's color response: its color shifts, saturation, and the effectiveness of its white balance algorithms.

5.7 Distortion is an aberration that causes straight lines to curve near the edges of images. It can be troublesome for architectural photography and metrology (photographic applications involving measurement). Distortion is worst in wide angle, telephoto, and zoom lenses. It often worse for close-up images than for images at a distance. It can be easily corrected in software.

5.8 Vignetting, or light falloff, darkens images near the corners. It can be significant with wide angle lenses.

5.9 Exposure accuracy can be an issue with fully automatic cameras and with video cameras where there is little or no opportunity for post-exposure tonal adjustment. Some even have exposure memory: exposure may change after very bright or dark objects appear in a scene.

5.10 Lateral chromatic aberration (LCA), also called "color fringing", including purple fringing, is a lens aberration that causes colors to focus at different distances from the image center. It is most visible near corners of images. LCA is worst with asymmetrical lenses, including ultrawides, true telephotos and zooms. It is strongly affected by demosaicing.

5.11 Lens flare, including "veiling glare" is stray light in lenses and optical systems caused by reflections between lens elements and the inside barrel of the lens. It can cause image fogging (loss of shadow detail and color) as well as "ghost" images that can occur in the presence of bright light sources in or near the field of view.

5.12 Color moiré is artificial color banding that can appear in images with repetitive patterns of high spatial frequencies, like fabrics or picket fences. It is affected by lens sharpness, the anti-aliasing (lowpass) filter (which softens the image), and demosaicing software. It tends to be worst with the sharpest lenses.

5.13 Artifacts – software (especially operations performed during RAW conversion) can cause significant visual artifacts, including Data compression and transmission losses (e.g. Low quality JPEG), oversharpening "halos" and loss of fine, low-contrast detail.

6. From analog to digital video

Since the time when the world's first video sequence was recorded, many video processing systems have been designed. In the ages of analog video systems, it was possible to evaluate quality of a video processing system by calculating the system's frequency response using some traditional test signal (for example, a collection of color bars and circles).

Nowadays, digital video systems are replacing analog ones, and evaluation methods have changed. Performance of a digital video processing system can vary significantly and depends on dynamic characteristics of input video signal (e.g. amount of motion or spatial details). That's why digital video quality should be evaluated on diverse video sequences, often from the user's database.

6.1 Objective video quality

Objective video evaluation techniques are mathematical models that approximate results of subjective quality assessment, but are based on criteria and metrics that can be measured objectively and automatically evaluated by a computer program. Objective methods are classified based on the availability of the original video signal, which is considered to be of high quality (generally not compressed). Therefore, they can be classified as FR, Reduced Reference Methods (RR) and NR. FR metrics compute the quality difference by comparing every pixel in each image of the distorted video to its corresponding pixel in the original video. RR metrics extract some features of both videos and compare them to give a quality score. They are used when all the original video is not available, e.g. in a transmission with a limited bandwidth. NR metrics try to assess the quality of a distorted video without any reference to the original video. These metrics are usually used when the video coding method is known.

The most traditional ways of evaluating quality of digital video processing system (e.g. video codec like DivX, Xvid) are calculation of the signal-to-noise ratio (SNR) and (PSNR) between the original video signal and signal passed through this system. PSNR is the most widely used objective video quality metric. However, PSNR values do not perfectly correlate with a perceived visual quality due to the non-linear behavior of the human visual system. Recently a number of more complicated and precise metrics were developed, for example UQI, VQM, PEVQ, SSIM,

VQuad-HD and CZD. Based on a benchmark by the Video Quality Experts Group (VQEG) in the course of the Multimedia Test Phase 2007-2008 some metrics were standardized as ITU-T Rec. J.246 (RR), J.247 (FR) in 2008 and J.341 (FR HD) in 2011.

The performance of an objective video quality metric is evaluated by computing the correlation between the objective scores and the subjective test results. The latter is called mean opinion score (MOS). The most frequently used correlation coefficients are : linear correlation coefficient, Spearman's rank correlation coefficient, kurtosis, kappa coefficient and outliers ratio.

When estimating quality of a video codec, all the mentioned objective methods may require repeating post-encoding tests in order to determine the encoding parameters that satisfy a required level of visual quality, making them time consuming, complex and impractical for implementation in real commercial applications. For this reason, much research has been focused on developing novel objective evaluation methods which enable prediction of the perceived quality level of the encoded video before the actual encoding is performed [1].

6.2 Subjective video quality

The main goal of many objective video quality metrics is to automatically estimate average user (viewer) opinion on a quality of video processed by the system. Sometimes however, measurement of subjective video quality can also be challenging because it may require a trained expert to judge it. Many “subjective video quality measurements” are described in ITU-T recommendation BT.500. Their main idea is the same as in Mean Opinion Score for audio: video sequences are shown to the group of viewers and then their opinion is recorded and averaged to evaluate the quality of each video sequence. However, details of testing may vary greatly.

6.3 Measurement of quality

PSNR, is an engineering term for the ratio between the maximum possible power of a signal and the power of corrupting noise that affects the fidelity of its representation. Because many signals have a very wide dynamic range, PSNR is usually expressed in terms of the logarithmic decibel scale. The PSNR is most commonly used as a measure of quality of reconstruction of lossy compression codecs (e.g., for image compression). The signal in this case is the original data, and the noise is the error introduced by compression. When comparing compression codecs it is used as an approximation to human perception of reconstruction quality, therefore in some cases one reconstruction may appear to be closer to the original than another, even though it has a lower PSNR (a higher PSNR would normally indicate that the reconstruction is of higher quality). One has to be extremely careful with the range of validity of this metric; it is only conclusively valid when it is used to compare results from the same codec (or codec type) and same content. It is most easily defined via MSE.

When the pixels are represented using 8 bits per sample, this is 255 MAXI is the maximum possible pixel value of the image. More generally, when samples are represented using linear PCM with B bits per sample, MAXI is $2^B - 1$. For color images with three RGB values per pixel, the definition of PSNR is the same except the MSE is the sum over all squared value differences divided by image size and by three. Alternately, for color images the image is converted to a different color space and PSNR is reported against each channel of that color space, e.g., YCbCr or HSL [11],[12],[13].

Typical values for the PSNR in lossy image and video compression are between 30 and 50 dB, where higher is better.[14],[15] Acceptable values for wireless transmission quality loss are considered to be about 20 dB to 25 dB.[16],[17]. When the two images are identical, the MSE will be zero. For this value the PSNR is undefined. Objective methods for assessing perceptual image quality traditionally attempted to quantify the visibility of errors (differences) between a distorted image and a reference image using a variety of known properties of the human visual system.

The PSNR block computes the peak signal-to-noise ratio, in decibels, between two images. This ratio is often used as a quality measurement between the original and a compressed image. The higher the PSNR the better the quality of the compressed or reconstructed image. MSE and the PSNR are the two error metrics used to compare image

compression quality. The MSE represents the cumulative squared error between the compressed and the original image, whereas PSNR represents a measure of the peak error. The lower the value of MSE, the lower the error.

6.4 Recommendation for Computing PSNR for Color Images

Different approaches exist for computing the PSNR of a color image. Because the human eye is most sensitive to luma information, compute the PSNR for color images by converting the image to a color space that separates the intensity (luma) channel, such as YCbCr. The Y (luma), in YCbCr represents a weighted average of R, G, and B. G is given the most weight, again because the human eye perceives it most easily. With this consideration, compute the PSNR only on the luma channel.

PSNR is generally used to analyze quality of image, sound and video files in dB (decibels). PSNR calculation of two images, one original and an altered image, describes how far two images are equal. Equation 1 shows the famous formula.

x: width of image.
 y: height.
 x*y: number of pixels (or quantities).

$$PSNR(dB) = 10 * \log\left(\frac{255^2}{MSE}\right)$$

$$MSE = \sum_{i=1}^x \sum_{j=1}^y \frac{(A_{ij} - B_{ij})^2}{x * y}$$

Equation 1.

7. Conclusion

Various processing techniques are involved in processing the image from the problem domain to the obtaining of results. The processed image is reconstructed to check the quality of the image. There are various reference methods to find the quality of the image. It might be subjective or objective. FR method or NF methods can be one adapted for assessment of quality of processed image. This processed image can be perceived by Human Visual System. Various assessment categories are available for assessing the image. The best way to assess the quality is by finding RMSE and PSNR. By finding this, quality of the processed image can be found. Therefore various categories and assessment of quality with respect to processed image, in this case a compressed image is considered and discussed.

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